根据websocket订阅将数据在地图上画出来

## websocket 订阅字典

var subDic = mapOf(

"/topic/vehicle" to "/avp/api/VL961/vehicle/1694264612474306561",//车辆位姿数据

"/topic/dataMerge" to "/avp/api/VL961/dataMerge",//感知目标物

"/topic/signal" to "/avp/api/VL961/signal",

"/topic/v2xStart" to "/avp/api/VL961/v2xStart",//v2x预警开始

"/topic/v2xEnd" to "/avp/api/VL961/v2xEnd",//v2x预警结束

"/topic/vehicleStatus" to "/avp/api/VL961/vehicleStatus",//联网车辆数据

"/topic/timeDelay" to "/avp/api/VL961/timeDelay",

"/topic/points" to "/avp/api/VL961/points",//停车位变更

"/topic/linePlaning" to "/avp/api/VL961/linePlaning",//全局路径发生切换

"/topic/partLine" to "/avp/api/VL961/partLine",// // 局部路径

"/topic/rsiEvent" to "/avp/api/VL961/rsiEvent",// rsi事件

)

## websocket回调字典

var dic = mapOf(

5231 to "/topic/vehicle",

5232 to "/topic/dataMerge",

5233 to "topic/signa",

5234 to "/topic/v2xStart",

5235 to "/topic/v2xEnd",

5236 to "/topic/vehicleStatus",

5237 to "/topic/timeDelay",

1 to "/topic/point",

52310 to "/topic/linePlaning",

52311 to "/topic/rsiEvent",

52312 to "/topic/partLine",

)

## 获取订单信息 getOrderData 后只有当avpStatus=3或5的时候需要路径规划

地锁：

地锁有四个状态 down(0, "已落下"),

up(1, "已升起"),

downing(2, "落下中"),

upping(3, "升起中"),

地锁状态变化时，会通过 /topic/parkingLockStatusChange 把状态发

地锁的初始状态 跟着车位列表一起返回给你了

## 问题

全局没有是因为路径没有发生切换

局部没有是因为路上没有障碍物，没有推送避障路线